

Unit IV Nonlinear Waves, Shocks and Turbulence - An Introduction

Previously discussed:

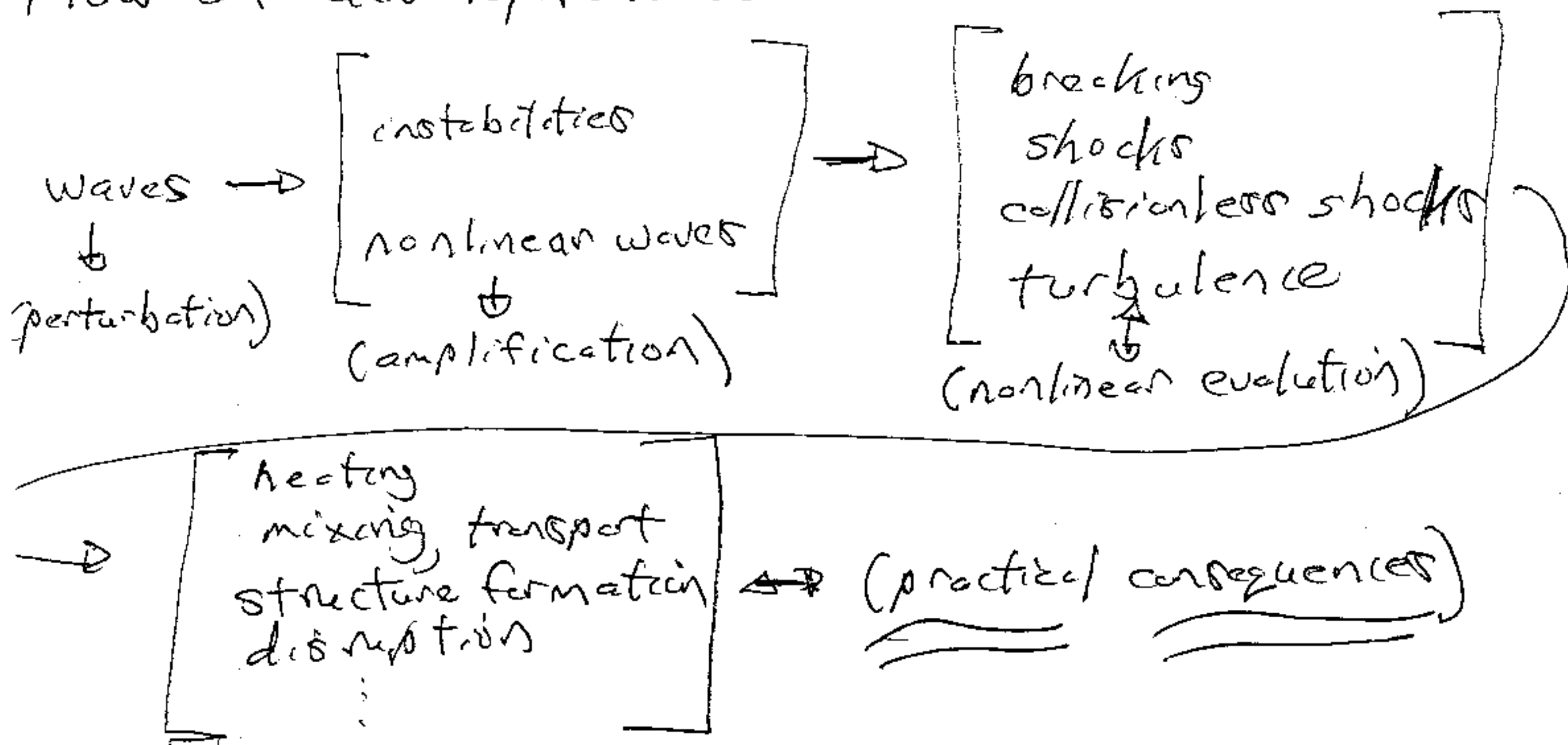
→ basic waves in MHD, i.e. structure of MHD 'stiffness matrix'

→ CW and MHD instabilities (an introduction)

Now are concerned with evolving waves and instabilities i.e. what happens? →

- non/linear amplification of MHD waves, wavebreaking
- shocks and collisionless shocks in MHD,
- turbulence

Flow of development is:



Proceed via :

i) Nonlinear Waves

- a) Wave Action and Eikonal Theory
- b) Wave Amplification and Breking
- c) Disparate Scale Interaction

ii) Shocks and collisionless shocks

- a) shocks in kinematic waves
- b) shocks in fluids and MHD
- c) collisionless shocks in plasmas

iii) Fluid and MHD Turbulence - An Introduction

then, ... \Rightarrow Applications to Laboratory and Solar Plasmas

① \rightarrow current and magnetic configurations (DW with J_0)

② \rightarrow ∇p stability of confinement devices

③ \rightarrow magnetic fields and buoyancy in the sun.

→ Nonlinear Waves

Read: { ① Kulsrud 5.5, 5.6
 ② Whitham, Chapt. 11
 ③ Landau, Lifshitz Fluids Chapt.

→ have considered plane waves in uniform media
 i.e. $\underline{\epsilon} \sim \underline{\epsilon}_0 e^{i(\underline{k} \cdot \underline{x} - \omega t)}$

→ what if media non-uniform, but slowly varying

i.e. $\frac{1}{c^2} \frac{\partial^2 \hat{\phi}}{\partial t^2} = \nabla^2 \hat{\phi}$ (caustics)

with $c^2 = c^2 / n^2(\underline{x})$

↳ index of refraction
 (can be time dependent)

then for $\left| \frac{\partial n}{n} \right| < |k|$, can write

$$\hat{\phi} = \hat{\phi}_0 e^{i\phi(\underline{x}, t)}$$

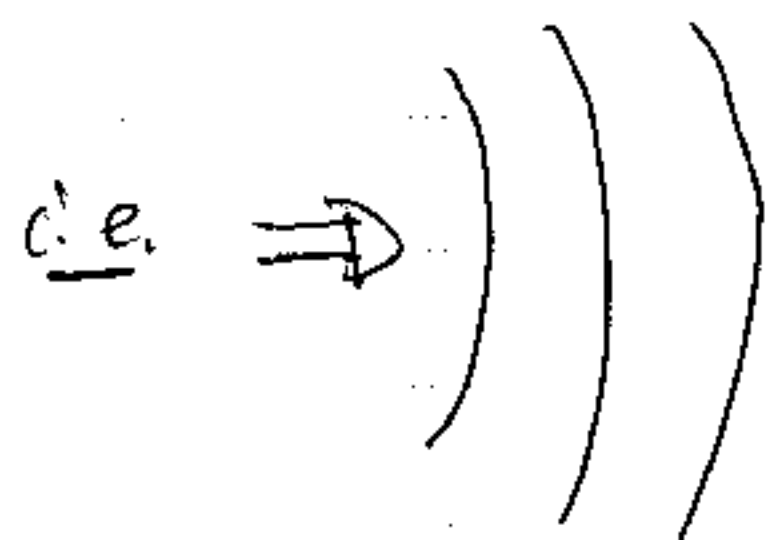
where $\phi \sim O(1/\epsilon)$

→ phase contains fastest variation

then have:

$$\boxed{\frac{n(\underline{x})^2}{c_0^2} \left(\frac{\partial \phi}{\partial t} \right)^2 = \left(\nabla \phi \right)^2}$$

→ eikonal equation
 for phase front
 function ϕ



i.e. ⇒ $\text{iso-}\phi$ surfaces ⇒ $\underline{\nabla} \phi$ ⇒ direction of propagation

clear analogy with plane waves \Rightarrow

$$\underline{\nabla} \phi \leftrightarrow \underline{k}$$

$$-\frac{\partial \phi}{\partial t} \leftrightarrow \omega$$

[if Λ time independent,
 $\omega = \text{const.}$ for linear wave]

so eikonal equation is:

$$\frac{n(x)^2}{c^2} \omega^2 = k^2$$

so, have for medium
with no explicit time dependence,

\hookrightarrow local dispersion
relation

$$d\phi = \frac{\partial \phi}{\partial x} \cdot dx + \frac{\partial \phi}{\partial t} dt$$

$$= \underline{k}(x) \cdot d\underline{x} - \omega(\underline{k}, x) dt$$

\hookrightarrow via Eikonal Equation

$$\therefore \frac{d\phi}{dt} = \underline{k}(x) \cdot \frac{d\underline{x}}{dt} - \omega(\underline{k}, x)$$

\Rightarrow

$$\Phi = \int dt \left[\underline{k}(x) \cdot \dot{\underline{x}} - \omega \right]$$

but recall:

$$\underbrace{S}_{\text{action}} = \int dt \left(\underbrace{p\dot{q} - H}_{\text{Hamiltonian}} \right) \quad \text{and} \quad \delta S = 0 \Rightarrow \text{equations of motion}$$

can immediately note analogy:

<p>Hamiltonian Dynamics</p>	<p>Rays/Eikonal Theory</p>
<p>\underline{p} → momentum (= $\partial L / \partial \dot{q}$)</p>	<p>\underline{k} (= $\nabla \phi$)</p>
<p>\underline{q} → gen. coord</p>	<p>\underline{x} (phase front position)</p>
<p>H → Hamiltonian</p>	<p>ω (frequency)</p>
<p>ϕ → phase function</p>	<p>S → action</p>

and recall Hamilton-Jacobi Equation:

$$\frac{\partial S}{\partial t} + H\left(q, \frac{\partial S}{\partial q}\right) = 0$$

⇒ phase evolution equation:

$$\frac{\partial \phi}{\partial t} + \omega(\underline{k}, \underline{x}) = 0$$

$$\underline{k} = \underline{\nabla} \phi$$

exact isomorphism

∴ just as advance Hamiltonian variables
on time via Hamilton's Egn. of Motion,
i.e.

$$\frac{d\underline{p}}{dt} = - \frac{\partial H}{\partial \underline{q}}, \quad \frac{d\underline{q}}{dt} = \frac{\partial H}{\partial \underline{p}}$$

then, can advance \underline{k} and \underline{x} analogously
by:

Ray
Eikonal
Equations

$$\frac{d\underline{k}}{dt} = - \frac{\partial \omega}{\partial \underline{x}} ; \quad \frac{d\underline{x}}{dt} = \frac{\partial \omega}{\partial \underline{k}} = \underline{v}_{gr}$$

Snell's Law

group velocity

$\underline{k} = \underline{\nabla} \phi \rightarrow$ phase front
orientation

$\underline{x} \rightarrow$ position of
phase front.

check: IF analogy is valid, should be able
to derive eikonal equations from $d\phi = 0$

$$\underline{\Phi} = \int dt \left[\underline{k} \cdot \underline{\dot{x}} - \omega(\underline{k}, \underline{x}) \right]$$

$$\delta \bar{\Phi} = \int dt \left[\underline{h} \cdot \delta \underline{\dot{x}} + \delta \underline{h} \cdot \underline{\dot{x}} - \left(\frac{\partial \omega}{\partial \underline{x}} \cdot \delta \underline{x} + \frac{\partial \omega}{\partial \underline{h}} \cdot \delta \underline{h} \right) \right]$$

$\delta \underline{x} = \delta \underline{h} = 0$ at end-points

\Rightarrow

$$\delta \bar{\Phi} = \int dt \left[\left(\underline{h} \cdot \frac{d}{dt} \delta \underline{x} - \frac{\partial \omega}{\partial \underline{x}} \cdot \delta \underline{x} \right) + \left(\underline{\dot{x}} - \frac{\partial \omega}{\partial \underline{h}} \right) \cdot \delta \underline{h} \right]$$

ibp

$$\delta \bar{\Phi} = \left. \underline{h} \cdot \delta \underline{x} \right|_{t_1}^{t_2} + \int dt \left[\left(\frac{d\underline{h}}{dt} + \frac{\partial \omega}{\partial \underline{x}} \right) \cdot \delta \underline{x} + \left(\underline{\dot{x}} - \frac{\partial \omega}{\partial \underline{h}} \right) \cdot \delta \underline{h} \right]$$

\Rightarrow

$\delta \underline{x}, \delta \underline{h} \neq 0 \Rightarrow$

$$\frac{d\underline{h}}{dt} = - \frac{\partial \omega}{\partial \underline{x}} \quad , \quad \frac{d\underline{x}}{dt} = \frac{\partial \omega}{\partial \underline{h}}$$

so \rightarrow eikonal equations are Hamiltonian equations

\rightarrow eikonal equations extremize $\bar{\Phi}$.

\rightarrow its eikonal equations satisfy Liouville's Theorem

ie "flow" in phase space $\underline{k}, \underline{x}$ is incompressible

$$\frac{\partial}{\partial \underline{k}} \cdot \frac{d\underline{k}}{dt} + \frac{\partial}{\partial \underline{x}} \cdot \frac{d\underline{x}}{dt} = -\frac{\partial^2 \omega}{\partial \underline{k} \partial \underline{x}} + \frac{\partial^2 \omega}{\partial \underline{x} \partial \underline{k}} = 0$$

\therefore so if define wave density $\rho(\underline{k}, \underline{x}, t)$

then $\frac{\partial \rho}{\partial t} + \underline{D}_{\underline{k}} \cdot (\underline{V}_{\underline{k}} \rho) = 0$

but $\underline{D} \cdot \underline{V}_{\underline{k}} = 0$

$$\underline{V}_{\underline{k}} = \left[\frac{d\underline{x}}{dt}, \frac{d\underline{k}}{dt} \right]$$

$$\Rightarrow \frac{\partial \rho}{\partial t} + \underline{V}_{\underline{k}} \cdot \underline{D}_{\underline{k}} \rho = 0$$

$$\frac{\partial \rho}{\partial t} + \underline{v}_{gr} \cdot \frac{\partial \rho}{\partial \underline{x}} - \frac{\partial \omega}{\partial \underline{x}} \cdot \frac{\partial \rho}{\partial \underline{k}} = 0$$

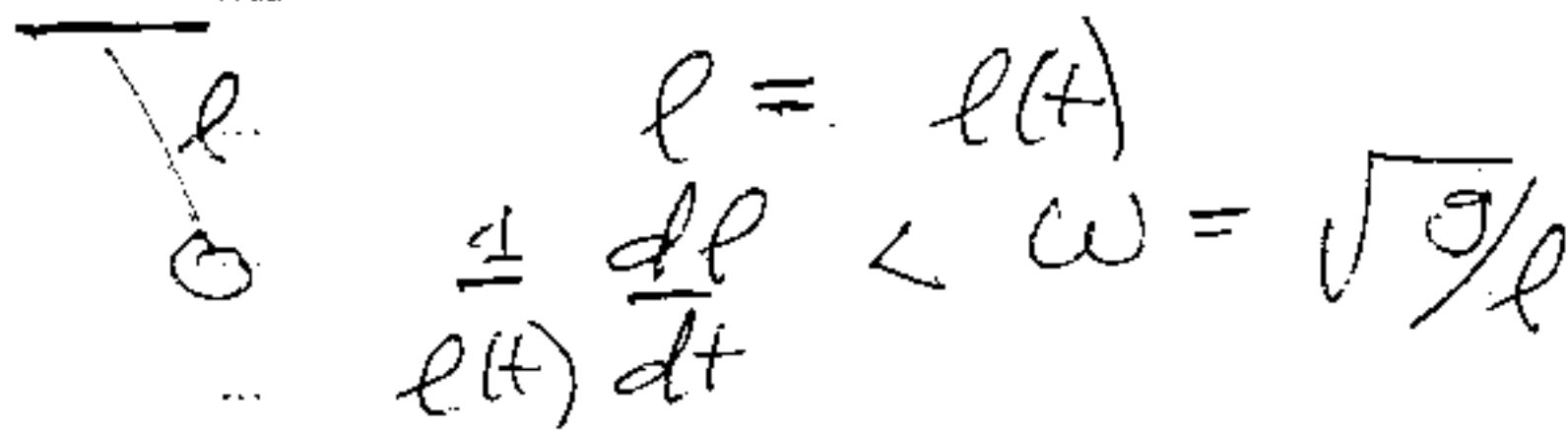
\Rightarrow Vlasov-like equation for evolution of ρ

but... what is ρ ?

\rightarrow physical argument:

have $\frac{d\rho}{dt} = 0 \rightarrow$ conservation/invariance principle

Now, recall for oscillator with slowly varying parameters



then $\frac{d}{dt} (E/\omega) = 0$

$E/\omega \equiv$ Action (dims energy * time)

$$E = 2 \cdot \frac{1}{2} m \omega^2 l^2 \Theta^2 = m g l \Theta^2$$

$$\frac{E}{\omega} = m\sqrt{g} l^{3/2} \Omega^2$$

$$\Rightarrow d(E/\omega) = 0 \Rightarrow \frac{3}{2} l^{1/2} \frac{dl}{dt} + l^{3/2} \frac{d\Omega^2}{dt}$$

$$d\Omega^2/dt = -\frac{3}{2} \frac{1}{l} \frac{dl}{dt}$$

\rightarrow l shortened ($\dot{l} < 0$)
amplitude increased

\rightarrow l lengthened,
amplitude decreased.

Now, for waves argue analogue of action
is wave action density $E/\omega = N$

E = energy density
 N = action density

so wave kinetic equation is:

$$\frac{\partial N}{\partial t} + \underline{v}_{gr} \cdot \frac{\partial N}{\partial \underline{x}} - \frac{\partial \omega}{\partial \underline{x}} \cdot \frac{\partial N}{\partial \underline{k}} = 0$$

and analogy with Vlasov equation is evident, i.e.

$$\frac{\partial f}{\partial t} + \underline{v} \cdot \frac{\partial f}{\partial \underline{x}} + \frac{\partial E}{\partial \underline{v}} \cdot \frac{\partial f}{\partial \underline{v}} = 0$$

$$\frac{dk}{dt} = - \left(\frac{\partial \omega}{\partial x} \right)_k \Rightarrow \text{no conflict with } \frac{dk}{dt} = - \frac{\partial \omega}{\partial x}$$

→ Now, if system independent of time, have:

$$\partial \omega / \partial t = 0$$

$$\begin{aligned} \text{so } \frac{d\omega}{dt} &= \frac{\partial \omega}{\partial t} + \frac{\partial \omega}{\partial k} \cdot \frac{dk}{dt} + \frac{\partial \omega}{\partial x} \cdot \frac{dx}{dt} \\ &= - \frac{\partial^2 \omega}{\partial k \partial x} + \frac{\partial^2 \omega}{\partial k \partial x} = 0 \quad \checkmark \end{aligned}$$

$$\left. \frac{dN}{dt} \right|_{\text{rays}} = 0 \Rightarrow \left. \frac{d}{dt} \begin{bmatrix} \Sigma \\ \bar{\omega} \end{bmatrix} \right|_{\text{rays}} = 0$$

$$\Rightarrow \left. \frac{d}{dt} \left(\frac{\Sigma}{\bar{\omega}} \right) \right|_{\text{rays}} - \frac{\Sigma}{\bar{\omega}^2} \left. \frac{d\bar{\omega}}{dt} \right|_{\text{rays}} = 0$$

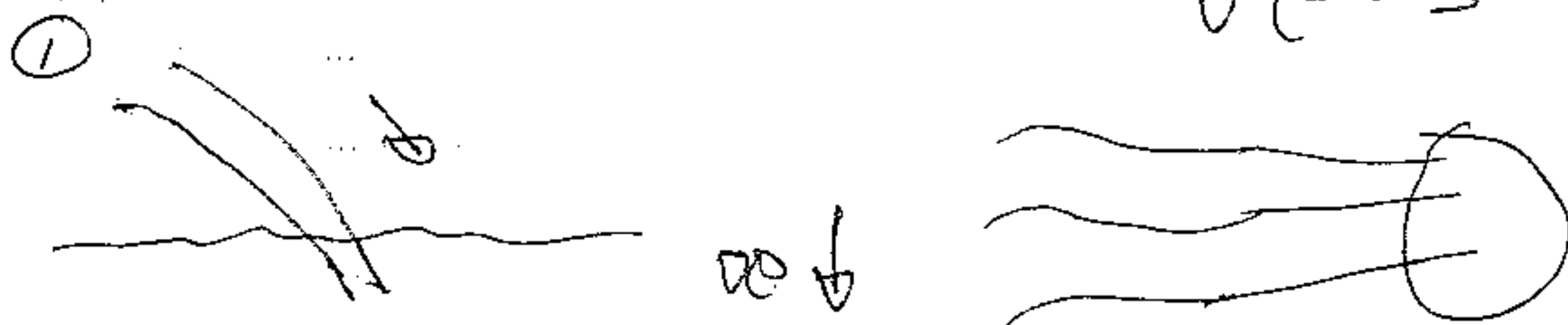
$$\Rightarrow \frac{\partial \Sigma}{\partial t} + \underline{v}_g \cdot \underline{\nabla} \Sigma - \frac{\partial \omega}{\partial x} \cdot \underline{\nabla}_k \Sigma = 0$$

and Liouville and integrate over $k \Rightarrow$

$$\frac{d\varepsilon}{dt} = \frac{\partial \varepsilon}{\partial t} + \nabla \cdot [v_{gr} \varepsilon] = 0$$

↓
applies to conservative case.

Applications



Alfvén wave packet incident on region with density increasing, field fixed.

c.e.

$$\nabla \cdot (v_{gr} \varepsilon) = 0$$

$$\underline{B} = B \hat{z}$$

$$\frac{\partial}{\partial z} (v_A \varepsilon) = 0$$

$$v_A = \frac{B}{\sqrt{4\pi\rho(z)}}$$

$$v_{A\infty} \varepsilon_{\infty} = v_A(z) \varepsilon(z)$$

↓
Inflow I

$$I = v_A(z) \epsilon(z)$$

$$= v_{A00} \sqrt{\frac{\rho_00}{\rho(z)}} \epsilon(z)$$

$$\Rightarrow \epsilon(z) = \left(\rho(z) / \rho_{00} \right)^{1/2} \epsilon_{00}$$

→ wave energy density increases in high density region

→ point is $v_{gr} \epsilon = \text{const}$

$v_{gr} = v_A \downarrow$ while $\rho \uparrow$, so ϵ does increase

How about displacement?

- very roughly speaking:

as wave is linearization, and assumes/predicts certain phase relation,

→ linear wave theory valid for

$$|k \tilde{\xi}| < 1$$

↳ wave slope



If $k \tilde{\epsilon} \sim 1 \Rightarrow$ expect strongly nonlinear behavior, breaking, mixing etc.

n.b. though for Alfvén waves, need add parallel compressibility....

$$\begin{aligned} \text{Now } \Sigma(z) &= 2 \rho \tilde{\epsilon}^2 \\ &= \rho(z) \omega^2 \tilde{\epsilon}^2 \end{aligned}$$

Now $\omega = \text{const}$

$$\begin{aligned} \text{so } \tilde{\epsilon}^2 &= \frac{1}{\rho(z) \omega^2} \left(\frac{\rho(z)}{\rho_0} \right)^{1/2} \epsilon_0 \\ &= \frac{1}{\sqrt{\rho(z) \rho_0}} \frac{\epsilon_0}{\omega^2} \end{aligned}$$

∴ displacement drops $\sim \rho(z)^{-1/4}$

as wave propagates into high density region.

but $\text{slope } S \sim |k \tilde{\epsilon}|$

$$k = \frac{\omega}{v_A} = \frac{\omega}{v_{A0}} \sqrt{\frac{\rho(z)}{\rho_0}}$$

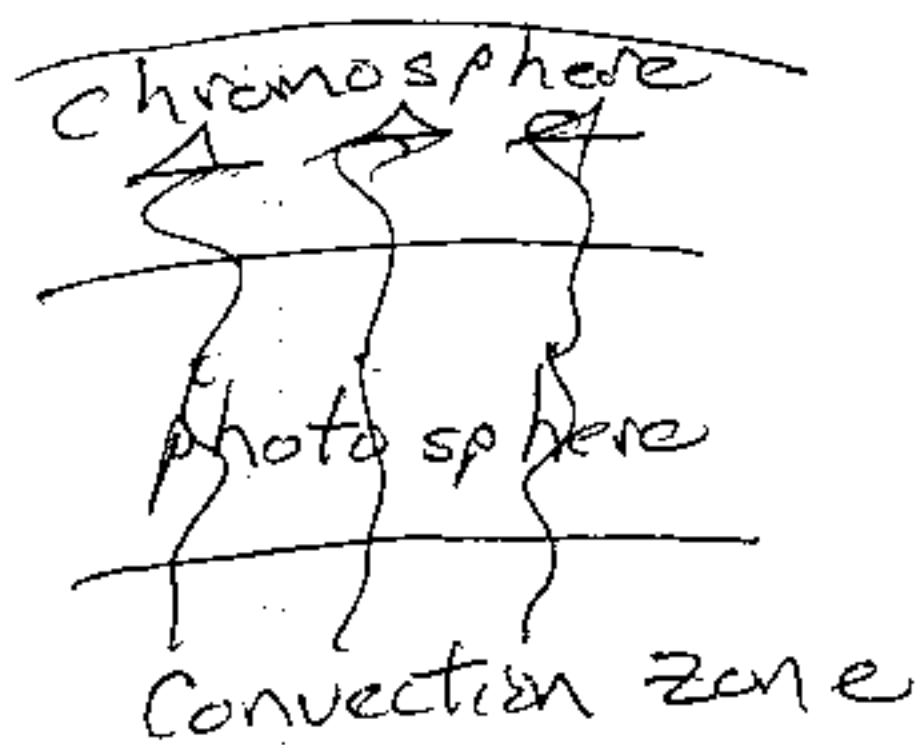
$$\Rightarrow |k \hat{\xi}| \sim \frac{\omega}{v_{A0}} \sqrt{\frac{\rho(z)}{\rho_0}} \left(\frac{E_0}{\omega}\right)^{1/2} \frac{1}{(\rho(z)\rho_0)^{1/4}}$$

$$\sim \rho(z)^{1/4}$$

\Rightarrow wave slope increases in high density region, as v_A changes

\Rightarrow Nonlinearity increases

② Sound propagating in chromosphere



$$\rho \sim e^{-z/H} \rightarrow \text{density decreases with height}$$

Sound waves emitted from convection zone (compressible convection) \rightarrow propagate into chromosphere

Take $T = \text{const} \Rightarrow c_s = \text{const.}$

Then $c_s \xi = \text{const.}$

$$\xi(z) = \text{const.}$$

and $k = \omega/c_s = \text{const.}$

$$\underline{\text{so}} \quad \rho \tilde{\xi}^2 = \text{const}$$

$$\rho(z) \omega^2 \tilde{\xi}^2 = \text{const}$$

$$\Rightarrow \tilde{\xi} = \left(\xi_{\infty} / \rho(z) \omega^2 \right)^{1/2} \sim 1 / (\rho(z))^{1/2}$$

$$\text{as } k = \text{const}, \quad k \tilde{\xi} \sim 1 / (\rho(z))^{1/2}$$

\Rightarrow - wave displacement increases in chromosphere

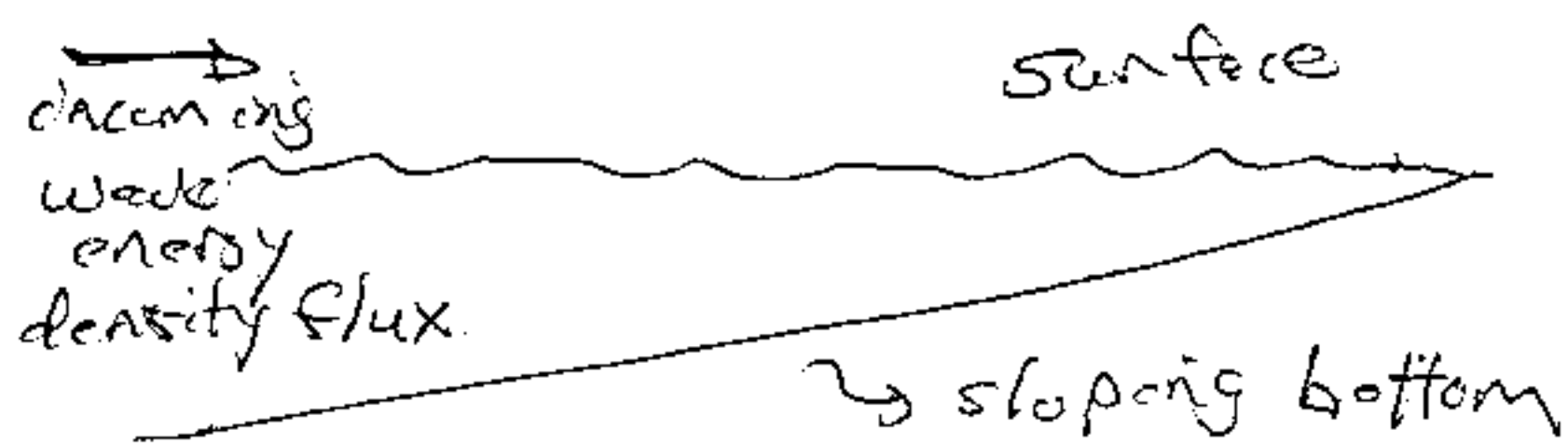
- sound wave simple \Rightarrow wave steepens and can shock

- physical picture is that of a whip \Rightarrow inertia at tip low, due tapering

- constitutes simple argument for chromospheric and possibly coronal heating by sound waves propagating from convection zone into upper layers.

(3) The beach....

Consider:



$$H = H(x)$$

Now, in shallow water
 $(\lambda > H)$



$$\frac{\partial h}{\partial t} + \frac{\partial (vh)}{\partial x} = 0$$

$$\frac{\partial v}{\partial t} + v \frac{\partial v}{\partial x} = -g \frac{\partial h}{\partial x}$$

$$v = v_0 + \tilde{v}, \quad h = H + \tilde{h}$$

$$\Rightarrow \begin{aligned} -i\omega \tilde{h} + ikH \tilde{v} &= 0 \\ -i\omega \tilde{v} &= -ikg \tilde{h} \end{aligned}$$

$\therefore \omega^2 = k^2 g H$ is dispersion relation

\Rightarrow analogy with acoustics is obvious

$$\begin{aligned} h &\leftrightarrow \psi & c_s^2 &= gH \\ v &\leftrightarrow \dot{\psi} & & \text{etc.} \end{aligned}$$

$$\frac{\partial \tilde{v}}{\partial t} = -g \frac{\partial \tilde{h}}{\partial x} \quad (1)$$

$$\frac{\partial \tilde{h}}{\partial t} = -H \frac{\partial \tilde{v}}{\partial x} \quad (2)$$

$$\Rightarrow (1) \times \tilde{v} + (2) \times \left(g \frac{\tilde{h}}{H} \right)$$

$$\therefore \frac{\partial \tilde{v}^2}{\partial t} = -g \tilde{v} \frac{\partial \tilde{h}}{\partial x}$$

$$\frac{g}{H} \frac{\partial \tilde{h}^2}{\partial t} = -\frac{gH}{H} \tilde{h} \frac{\partial \tilde{v}}{\partial x}$$

$$\therefore \frac{\partial}{\partial t} \left(\frac{\tilde{v}^2}{2} + \frac{g\tilde{h}^2}{2H} \right) + \frac{\partial}{\partial x} \left(g\tilde{h}\tilde{v} \right) = 0$$

is energy theorem

$$\Rightarrow \Sigma = \frac{\tilde{v}^2}{2} + \frac{g\tilde{h}^2}{2H} \quad \text{is wave energy density}$$

$$\omega/k = (gH)^{1/2} \quad \text{is wave phase velocity}$$

so ... as no explicit time dependence:

$$\frac{\partial \Sigma}{\partial t} + \nabla \cdot (v_{gr} \Sigma) = 0$$

$$\Rightarrow v_g(x) \Sigma(x) = v_{\infty} \Sigma_{\infty} = I$$

$$\therefore \sqrt{gH(x)} \Sigma(x) = I$$

\Rightarrow as $x \rightarrow \text{shore}$, $v_g \downarrow$ so $|\Sigma(x)|$ must increase

$$\Sigma(x) = \frac{\tilde{v}^2}{2} + g \frac{\tilde{v}^2}{2H} = \overline{\tilde{v}^2}$$

\rightarrow horizontal displacement

$$\tilde{v} = \frac{\partial \Sigma}{\partial t}$$

$$\Sigma(x) = \rho_0 \omega^2 \overline{\tilde{\epsilon}^2} \quad \text{and } \rho_0 \omega^2 = \text{const, here}$$

$$\Rightarrow \tilde{\epsilon}_{rms} \sim \left(\frac{I}{\rho_0 \omega^2 \sqrt{gH(x)}} \right)^{1/2} \sim H(x)^{-1/4}$$

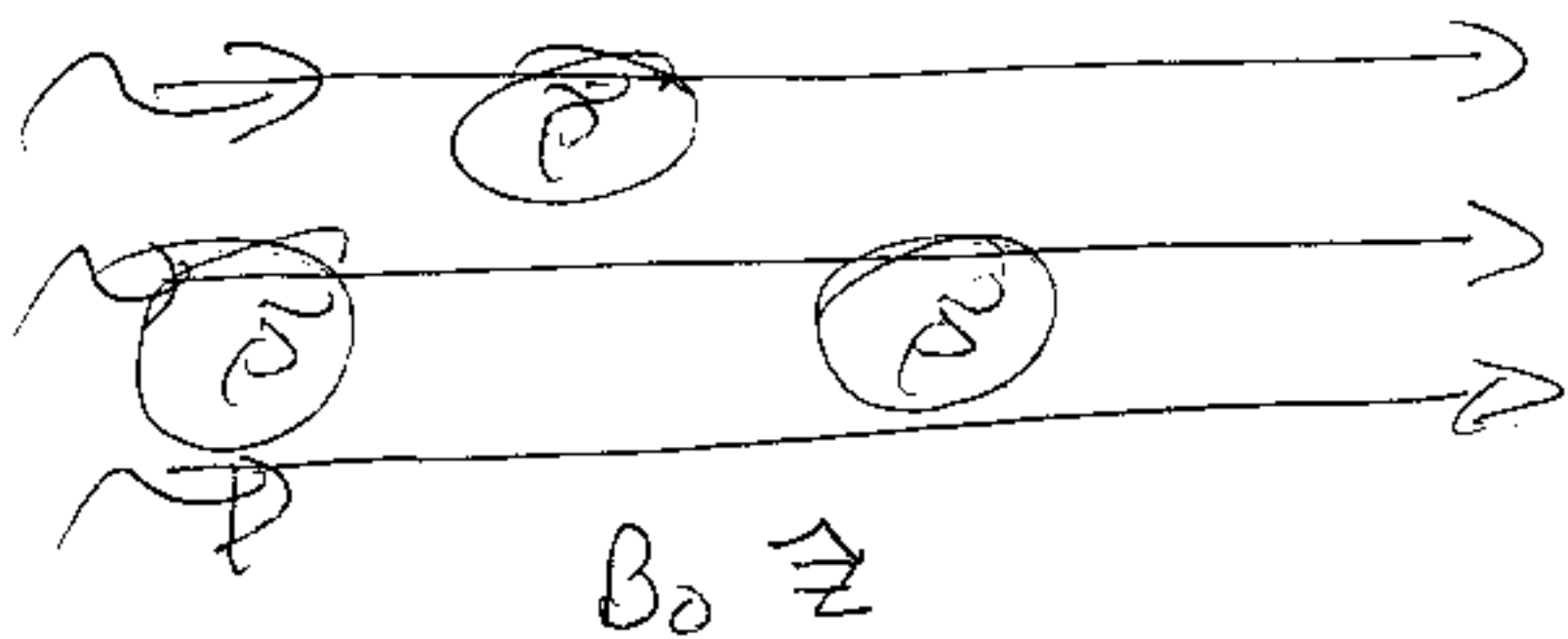
for profile $H(x)$, can deduce displacement profile

N.B. If $H = H(x, y)$, wavefronts align with bottom depth, via refraction.

$$\text{i.e. } \frac{dk}{dt} = -\frac{\partial \omega}{\partial x} = -\frac{\partial}{\partial x} \left[(gH(x, y))^{1/2} k \right]$$

(4) Alfven Waves in Random Medium

Consider straight B_0 threading medium
with space-time dependent inhomogeneities



i.e. $\rho_0 + \tilde{\rho}$
with $\langle \tilde{\rho}^2 \rangle_{q, \Omega}$ given.

How does spectrum of Alfven waves evolve?

Assume: $|q| \ll |k|$
 $\Omega \ll |k v_A|$ } \rightarrow clear scale separation
between scatterer
and scatter-ee
and weak inhomogeneities
($\tilde{\rho} \ll \rho_0$)

What happens?

$$\frac{dx}{dt} = v_{gr} = v_A$$

$$\frac{dk}{dt} = -\frac{\partial}{\partial x} \cdot (k_{||} v_A)$$

$$v_A = \frac{B_0}{\sqrt{4\pi\rho}} \approx v_{A0} \left(1 - \frac{\tilde{\rho}}{2\rho_0} \right)$$

take 1.0 for simplicity:

$$\frac{dz}{dt} = v_{A0} \left(1 - \frac{1}{2} \frac{\tilde{\rho}}{\rho_0} \right) = v_{A0} (1 - d\rho)$$

$$\begin{aligned} \frac{dk_z}{dt} &= - \frac{\partial}{\partial z} \left(k_z v_{A0} \left(1 - \frac{\tilde{\rho}}{2\rho_0} \right) \right) && \text{refraction} \\ &= \frac{\partial}{\partial z} \left(k_z v_{A0} \frac{\tilde{\rho}}{2\rho_0} \right) = \frac{\partial}{\partial z} k_z v_{A0} d\rho && \text{action} \end{aligned}$$

How does Alfvén spectrum respond to this?

⇒ wave kinetics!

$$\frac{\partial N}{\partial t} + \underline{v}_{gr} \cdot \underline{\nabla} N - \frac{\partial \omega}{\partial x} \cdot \frac{\partial N}{\partial k} = 0$$

$$N = \sum(k, x) / \omega$$

$$\frac{\partial N}{\partial t} + v_{A0} (1 - d\rho) \hat{z} \cdot \underline{\nabla} N + \frac{\partial}{\partial z} \left(k_z v_{A0} d\rho \right) \frac{\partial N}{\partial k_z} = 0$$

Now $d\rho$ is - random variable
- spectrum specified

∴ for trends need average

⇒

$$\frac{\partial \langle N \rangle}{\partial t} + \left\langle v_{A0}(1-d\rho) \bar{z} \cdot \nabla N \right\rangle + \left\langle \frac{\partial}{\partial z} (k_z v_{A0} d\rho) \frac{\partial N}{\partial k_z} \right\rangle = 0$$

and average contributions will come from

$\langle d\rho \delta N \rangle$ type correlations.

∴ proceed in spirit of quasi-linear theory.

Using $\nabla_{\perp} \cdot \underline{v}_{\perp} = 0 \Rightarrow$

$$\frac{\partial \langle N \rangle}{\partial t} - \frac{\partial}{\partial z} \left\langle v_{A0} d\rho \delta N \right\rangle + \frac{\partial}{\partial k_z} \left\langle \frac{\partial (k_z v_{A0} d\rho)}{\partial z} \delta N \right\rangle = 0$$

where we have taken $\langle N \rangle$ indep. of z
(uniform beam).

Now, to calculate correlations $\langle d\rho \delta N \rangle$,

$\left\langle \frac{\partial d\rho}{\partial z} \delta N \right\rangle$, use linear response for δN

Linearizing WKE:

$$\frac{\partial \delta N}{\partial t} + v_A \frac{\partial \delta N}{\partial z} = v_A \frac{\partial \rho}{\partial z} \frac{\partial \langle N \rangle}{\partial z} - \frac{\partial (k_z v_A \delta \rho)}{\partial z} \frac{\partial \langle N \rangle}{\partial k_z}$$

homogeneous background

$$\Rightarrow -i(\Omega - \omega) \delta N_{\Omega, \omega} = -i \sum k_z v_A \delta \rho_{\Omega, \omega} \frac{\partial \langle N \rangle}{\partial k_z}$$

$$\therefore \delta N_{\Omega, \omega} = \frac{\sum k_z v_A \delta \rho_{\Omega, \omega}}{(\Omega - \omega)} \frac{\partial \langle N \rangle}{\partial k_z}$$

\Rightarrow

$$\frac{\partial \langle N \rangle}{\partial t} = \frac{\partial}{\partial k_z} D_{k_z} \frac{\partial \langle N \rangle}{\partial k_z} \quad \leadsto \text{quasi-linear diffusion equation for } \langle N \rangle$$

$$A_{k_z} = \sum_{\Omega, \omega} \omega^2 k_z^2 v_A^2 |\delta \rho_{\Omega, \omega}|^2 \pi \delta(\Omega - \omega)$$

$$= \sum_{\omega} \pi k_z^2 \omega^2 v_A^2 |\delta \rho_{\omega, \omega}|^2$$

resonance between $\frac{\omega}{\omega}$ and $v_{gr} = v_A$
 \hookrightarrow packet group velocity.
 stream field phase velocity

Note:

- basic gist of answer to question is that random inhomogeneities diffuse $\langle V \rangle$ spectrum in k_z
- physics clear from treating eikonal equation as Langevin equation

c.e.
$$\frac{dk_z}{dt} = -\frac{\partial}{\partial z} V_A(z)$$

$$= -\frac{\partial}{\partial z} \left(V_0 \left(1 - \frac{1}{2} \frac{\delta^2}{\epsilon_0} \right) k_z \right)$$

k_z in k_z due to inhomog.

$$\frac{dk_z}{dt} = V_{A0} k_z \frac{\partial}{\partial z} \delta^2$$

stochastic refraction

$$\Rightarrow \langle \delta k_z^2 \rangle \approx D t$$

$$D \approx V_{A0}^2 k_z^2 \left\langle \left| \frac{\partial}{\partial z} \delta^2 \right|_{\mathcal{N}_0}^2 \right\rangle \equiv D_{k_z}$$

- what is \mathcal{N}_0 ?

\Rightarrow set by spectrum of inhomogeneities

c.e. here Ω, \mathcal{E} independent

\rightarrow scatterers not waves \rightarrow width $\Delta \mathcal{E}$

$$\propto |\tilde{\rho}|_{\mathcal{E}, \Omega}^2 = |\tilde{\rho}(\mathcal{E})|^2 \frac{\Delta \Omega}{\Omega^2 + (\Delta \Omega)^2}$$

then $\tau_c = \min \left\{ 1/\Delta \Omega, 1/\Delta \mathcal{E} v_A \right\}$

contrast to usual case:

$$\frac{\partial \langle F \rangle}{\partial t} = \frac{\partial}{\partial V} D \frac{\partial \langle F \rangle}{\partial V}$$

$$0 = \sum_{\mathbf{k}} \frac{q^2}{m^2} |E_{\mathbf{k}}|^2 \pi \delta(\omega_{\mathbf{k}} - kv)$$

and $\tau_{\text{rel}} \sim |k(V_{\text{ph}} - V_{\text{gr}})|^{-1}$

\rightarrow dispersion time for eigenmode packet

when is QLT applicable? - $\left\{ \begin{array}{l} \text{equivalent to asking} \\ \text{when valid to treat} \\ \text{problem as stochastic} \end{array} \right.$

— basically, ① weak scattering
② resonance overlap

most clearly seen in context of particle

Need: 

$$\tau_{\text{sc}} < \tau_{\text{bounce}}$$

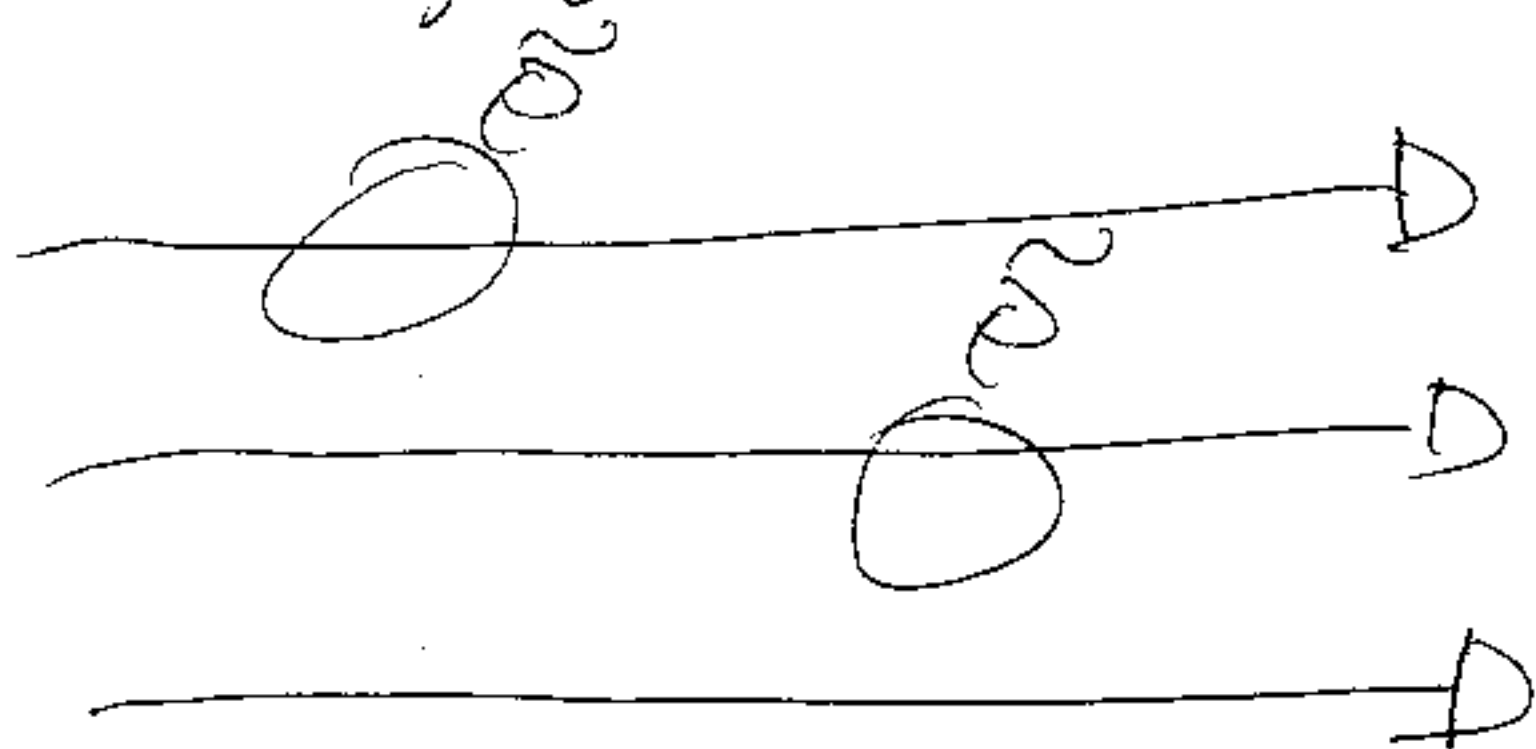
$$1/\tau_{\text{bounce}} \sim k \left(\frac{gH}{m} \right)^{1/2}$$

so linearization valid.

→ What is the bottom line? ⇒ spectrum
spreads diffusively

in particular, high k_z 's generated.

⑤ Now, go one step further ----



c.i.e. waves
Alfven \oplus
ion-acoustic waves

⇒ associate scattering field

— not with randomly prescribed inhomogeneities

- rather, with a field of ion acoustic waves

so in 1D

→ high frequency, short wavelength Alfvén waves
and $\omega = k_z v_A$

→ low frequency, longer wavelength ion acoustic waves

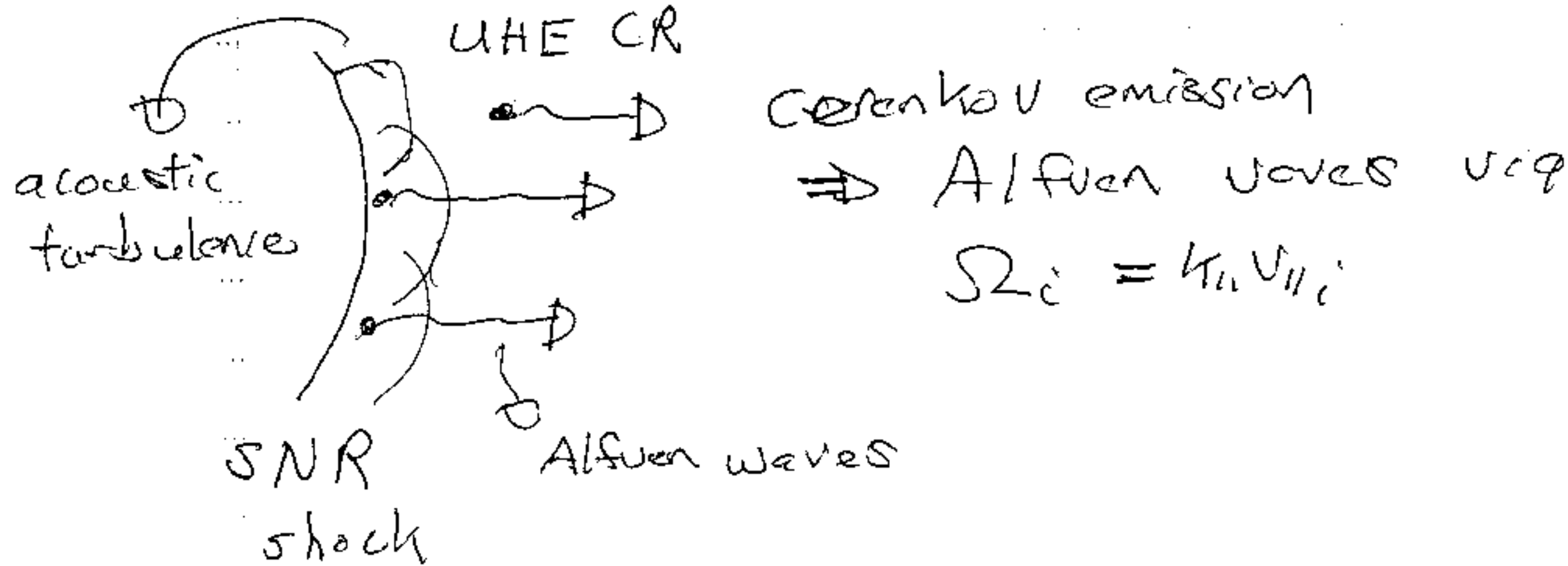
$$\Omega^2 = \frac{Z^2 C_s^2}{1 + \underbrace{Z^2 \lambda_D^2}}_{}^2$$

↳ dispersion due
Debye screening

- N.B.
- this is really a 'nonlinear' problem (very similar to SRS, SBS, Langmuir turbulence)
 - but, using eikonal methods, can be treated with linear, quasi-linear methodology
 - the "hidden smallness parameter" is scale ratio

$$\frac{\Omega}{\omega} \ll 1, \quad \frac{Z}{k_z} \ll 1$$

- what might this be useful for, apart from trial-by-ordeal?



so - have environment where spectrum of Alfven waves co-exists with spectrum of acoustic-type density perturbations.

- interaction could be relevant to process of CR acceleration

N.B. Of course, it is a bit more complicated ...

\rightarrow What new feature enters here?

- eikonal games

- dynamical coupling of high and low frequency waves

⇒ effective pressure of Alfvén waves on acoustic wave!

⊕

⇒ refraction of Alfvén waves by acoustic waves as before

Now, in 1D, recall ion-acoustic wave has:

$$\nabla^2 \tilde{\phi} = 4\pi n_0 |e| (\tilde{n}_i - \tilde{n}_e)$$

$$\frac{\tilde{n}_e}{n_0} = \frac{|e| \tilde{\phi}}{T_e} \quad (\omega \ll k v_{Te})$$

⇒ Boltzmann response

and for ions:

$$\frac{\partial n}{\partial t} + \frac{\partial (nv)}{\partial x} = 0$$

$$\frac{\partial v}{\partial t} + v \frac{\partial v}{\partial x} = \left(\frac{|e| E}{m n} \right) - \frac{1}{nm} \frac{\partial p}{\partial x}$$

$$E = -\partial \phi / \partial x$$

To make easier, treat as 1 fluid, with dispersion later added "by hand".

⇒

$$\frac{\partial \rho}{\partial t} + \frac{\partial (\rho v)}{\partial x} = 0$$

$$\frac{\partial v}{\partial t} + v \frac{\partial v}{\partial x} = -\frac{1}{\rho} \frac{\partial p}{\partial x}$$

i.e. magnetic field irrelevant to parallel-to- B_0 acoustic wave.

now here, have: $P = P_{Th}$.

With Alfvén waves (and 1D), let

$$P \rightarrow P_{Th} + P_{AW_{eff}}$$

n.b. for technical reasons, need weak dispersion in Alfvén waves

but $P_{AW_{eff}} = \epsilon_{AW}$ i.e. $\omega^2 = k_{||}^2 v_A^2 / (1 + k_{||}^2 c^2 / \omega_p^2)$

↳ energy density of Alfvén waves δ ignore till needed

$$= \int dk \omega_n N_n$$

↳ Action density of Alfvén waves.

so, in linear theory for acoustic wave:

$$\frac{\partial \tilde{\rho}}{\partial t} = -\rho_0 \frac{\partial \tilde{v}}{\partial x}$$

$$\frac{\partial \tilde{v}}{\partial t} = -\frac{1}{\rho_0} \frac{\partial}{\partial x} \left(\tilde{p} + \tilde{p}_{AW} \right)$$

$$\tilde{p} = \gamma \rho_0 \left(\tilde{\rho} / \rho_0 \right)$$

$$\tilde{p}_{AW} = \int dk \omega_k \tilde{N}_k$$

from wave kinetic equation

⇒

$$\rho_0 \frac{\partial}{\partial t} \left(\frac{\partial \tilde{v}}{\partial x} \right) = -\frac{\partial^2}{\partial x^2} \left(\gamma \rho_0 \tilde{\rho} + \tilde{p}_{AW} \right)$$

$$\Rightarrow \frac{\partial^2 \tilde{\rho}}{\partial t^2} = \frac{\partial^2}{\partial x^2} \left(\underbrace{\gamma \rho_0}_{c_s^2} \tilde{\rho} + \tilde{p}_{AW} \right)$$

Now, need calculate \tilde{p}_{AW} !

$$\frac{\partial N}{\partial t} + \underline{v}_{gr} \cdot \nabla N - \frac{\partial \omega}{\partial x} \cdot \frac{\partial N}{\partial k} = 0$$

and linearizing as before \Rightarrow

$$\frac{\partial \delta N}{\partial t} + v_A \frac{\partial \delta N}{\partial z} = - \frac{\partial}{\partial z} \left(k_z \frac{v_A \tilde{\rho}}{2\rho_0} \right) \frac{\partial \langle N \rangle}{\partial k_z}$$

\Rightarrow

$$\delta N_{\Omega, z} = \frac{2k_z v_A}{(\Omega - 2v_A)} \left(\frac{\tilde{\rho}}{2\rho_0} \right)_{\Omega, z} \frac{\partial \langle N \rangle}{\partial k_z}$$

$$-\Omega^2 \tilde{\rho}_{\frac{\Omega}{2}} = -\Sigma^2 \left(c_s^2 \tilde{\rho}_{\frac{\Omega}{2}} + \int dk_z (k_z v_A) \delta N_{\frac{\Omega}{2}} \right)$$

$$(\Omega^2 - \Sigma^2 c_s^2) \tilde{\rho}_{\frac{\Omega}{2}} = -\Sigma^2 \int dk_z (k_z v_A) \left(\frac{2k_z v_A / 2}{\Omega - 2v_A} \right) \left(\frac{\tilde{\rho}_{\frac{\Omega}{2}}}{\rho_0} \right) \frac{\partial \langle N \rangle}{\partial k_z}$$

and convenient to write as

$$(\Omega^2 - g^2 c_s^2) \tilde{\rho}_{g,\Omega} = -g^2 \int dk_z \left[\frac{k_z v_A \langle N \rangle}{\rho_0} \right] \left(\frac{g k_z (v_A/2)}{\Omega - 2v_A} \right) \frac{1}{\langle N \rangle} \frac{\partial \langle N \rangle}{\partial k} \tilde{\rho}_{g,\Omega}$$

$\{$
 $E_g/\rho_0 \sim \frac{P_{eff}}{\rho_0}$

⇒ have recovered a variant of Landau problem?

$$(\Omega^2 - g^2 c_s^2) = -g^2 \int dk_z \left(\frac{P_{eff}}{\rho_0} \right) \left(\frac{g k_z (v_A/2)}{\Omega - 2v_A} \right) \frac{1}{\langle N \rangle} \frac{\partial \langle N \rangle}{\partial k}$$

→ effective "radiation pressure" of Alfvén waves modifies acoustic mode

→ $v_A = \Omega(g)/g$ resonance

⇒ Landau-like growth/damping

key is $\left. \frac{\partial \langle N \rangle}{\partial k} \right|_{res.} \Leftrightarrow \text{sign} \left. \frac{\partial f}{\partial v} \right|_{res.}$

Now, can proceed vice P.T. if $\rho_{\text{eff}}/\rho_0 < 1 \Rightarrow$

$$(\Omega_0 + i\gamma) - \Sigma^2 c_s^2 = -\Sigma^2 \int dk_z \left(\frac{\rho_{\text{eff}}}{\rho_0} \right) \frac{g k_z (V_A/2)}{\Omega - 2V_A} \frac{1}{\langle N \rangle} \frac{\partial \langle N \rangle}{\partial k}$$

$$i 2 \Sigma c_s \gamma = \Sigma^2 \int dk_z \left(\frac{\rho_{\text{eff}}}{\rho_0} \right) \frac{g k_z V_A}{2} \pi \delta(\Omega - 2V_A) \frac{1}{\langle N \rangle} \frac{\partial \langle N \rangle}{\partial k}$$

$$\Rightarrow \gamma_2 = \frac{\Sigma^2}{c_s} \left(\frac{\rho_{\text{eff}}}{\rho_0} \right) \frac{V_A}{4} \int dk_z k_z \pi \delta(\Omega - 2V_A) \frac{1}{\langle N \rangle} \frac{\partial \langle N \rangle}{\partial k}$$

???

- point here is that no way to resolve/understand singularity, as Alfven waves are non-

dispersive!

- one solution: go outside MHD to introduce dispersion!

i.e. retaining Hall term \Rightarrow
(i.e. earlier comment)

$$\omega^2 = k_z^2 V_A^2 / (1 + k_z^2 d_s^2)$$

$$d_s^2 = c^2 / \omega_{pe}^2$$

∴ then have:

$$\gamma_2 = \frac{g^2}{c_s^2} \left(\frac{P_{eff}}{\rho_0} \right) \frac{V_A}{4} \int dk_z k_z \pi c'(\Omega - \Sigma V_{gr}(k)) \frac{1}{\langle N \rangle} \frac{\partial \langle N \rangle}{\partial k}$$

and resonant k identified! → proceed abt London

2 lessons:

→ population inversion, i.e. $\frac{\partial \langle N \rangle}{\partial k} > 0$, needed

for growth. Also
to $\partial f / \partial v > 0$.

→ makes important point that non-dispersive waves all strained at same rate, so no Doppler dispersion

⇒ non-dispersive waves steeper → shocks, etc. in MHD

→ can compute $\langle N \rangle$ evolution abt QLT ,
 $\Omega(z)$ dispersion relevant.